

6. MAC 093

6.1. Technical Data

Designation	Symbol	Unit	Motor type MAC ...		
			093 A - - - WS	093 B - - - OS	093 C - - - KS
Nominal motor speed ¹⁾	n	min ⁻¹	2000	2000	2000
Continuous torque at standstill ²⁾	M _{dN}	Nm	9.2 (12.0) ⁵⁾	14.5 (20.0) ⁵⁾	19.5 (28.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	11(14) ⁵⁾	18 (25) ⁵⁾	22 (32) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	22 x 10 ⁻⁴	29 x 10 ⁻⁴	42 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.875	0.831	0.910
Windings resistance at 20 °C	R _A	Ohm	1.313	0.625	0.433
Windings inductance	L _A	mH	16.0	9.0	7.0
Maximum peak of pulse current	I _{peak}	A	54	89	110
Thermal time constant	T _{th}	min	50 (30) ⁵⁾	50 (45) ⁵⁾	50 (45) ⁵⁾
Mass ⁴⁾	m _M	kg	13.0	16.5	22.0
			093 A - - - PS	093 B - - - JS	093 C - - - FS
Nominal motor speed ¹⁾	n	min ⁻¹	3000	3000	3000
Continuous torque at standstill ²⁾	M _{dN}	Nm	9.2 (12.0) ⁵⁾	14.5 (18.3) ⁵⁾	19.5 (28.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	15 (20) ⁵⁾	27 (34) ⁵⁾	35 (50) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	22 x 10 ⁻⁴	29 x 10 ⁻⁴	42 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.620	0.554	0.579
Windings resistance at 20 °C	R _A	Ohm	0.659	0.227	0.175
Windings inductance	L _A	mH	8.0	4.0	2.9
Maximum peak of pulse current	I _{peak}	A	76	134	173
Thermal time constant	T _{th}	min	50 (45) ⁵⁾	50 (45) ⁵⁾	50 (45) ⁵⁾
Mass ⁴⁾	m _M	kg	13.0	16.5	22.0
			093 A - - - LS	093 B - - - GS	093 C - - - DS
Nominal motor speed ¹⁾	n	min ⁻¹	4000	4000	4000
Continuous torque at standstill ²⁾	M _{dN}	Nm	9.2 (12.0) ⁵⁾	14.5 (20.0) ⁵⁾	19.5 (28.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	22 (28) ⁵⁾	38 (53) ⁵⁾	48 (69) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	22 x 10 ⁻⁴	29 x 10 ⁻⁴	42 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.438	0.388	0.413
Windings resistance at 20 °C	R _A	Ohm	0.328	0.136	0.089
Windings inductance	L _A	mH	4.0	2.0	1.5
Maximum peak of pulse current	I _{peak}	A	108	192	242
Thermal time constant	T _{th}	min	50 (45) ⁵⁾	50 (45) ⁵⁾	50 (45) ⁵⁾
Mass ⁴⁾	m _M	kg	13.0	16.5	22.0
			093 A - - - HS	093 B - - - ES	093 C - - - CS
Nominal motor speed ¹⁾	n	min ⁻¹	6000	6000	6000
Continuous torque at standstill ²⁾	M _{dN}	Nm	9.2 (9.8) ⁵⁾	14.5 (20.0) ⁵⁾	19.5 (28.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	32 (34) ⁵⁾	54 (74) ⁵⁾	60 (87) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	22 x 10 ⁻⁴	29 x 10 ⁻⁴	42 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.292	0.277	0.331
Windings resistance at 20 °C	R _A	Ohm	0.146	0.069	0.057
Windings inductance	L _A	mH	1.8	1.0	0.9
Maximum peak of pulse current	I _{peak}	A	162	268	302
Thermal time constant	T _{th}	min	50 (45) ⁵⁾	50 (45) ⁵⁾	50 (45) ⁵⁾
Mass ⁴⁾	m _M	kg	13.0	16.5	22.0

¹⁾ The usable motor speed is determined by the drive used.
Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.

²⁾ With 60K overtemperature at the motor housing.
Continuous torque can be limited by the drive. See selection data.

³⁾ With tacho-generator, without holding brake

⁴⁾ With tacho-generator, without holding brake, without blower.

⁵⁾ Parenthetical values apply to versions with surface cooling.

Fig 6.1: Type-dependent motor data

Designation	Symbol	Unit	Data	
Permissible ambient temperature	T_{um}	°C	0 ... + 45	
Permissible storage and transport temperature	T_L	°C	-20 ... +80	
Maximum installation elevation		m	1000 m. above sea level	
Protection category			IP 65	
Insulation classification			F	
Housing coat			Black prime coat (RAL 9005)	
Voltage constant of the tachogenerator ¹⁾	C_w	Vs/rad V/min ⁻¹	0.0143 1.5/1000	0.0286 3/1000

¹⁾ Tachovoltage can be selected application-related.

Fig 6.2: General data MAC 093

Designation	Symbol	Unit	Data holding brake		
			Standard	heavy-duty electrically actuated release	extra heavy-duty
Principle of action					
Holding torque	M_H	Nm	6.5	14	22
Nominal voltage	U_N	V		DC 24 ± 10%	
Nominal current	I_N	A	0.7	0.7	0.7
Moment of inertia	J_B	kgm ²	1.06×10^{-4}	3.6×10^{-4}	3.6×10^{-4}
Release delay	t_L	ms	60	70	70
Clamping delay	t_k	ms	20	30	30
Mass	m_B	kg	0.6	1.1	1.1

Fig 6.3: Technical data - holding brake

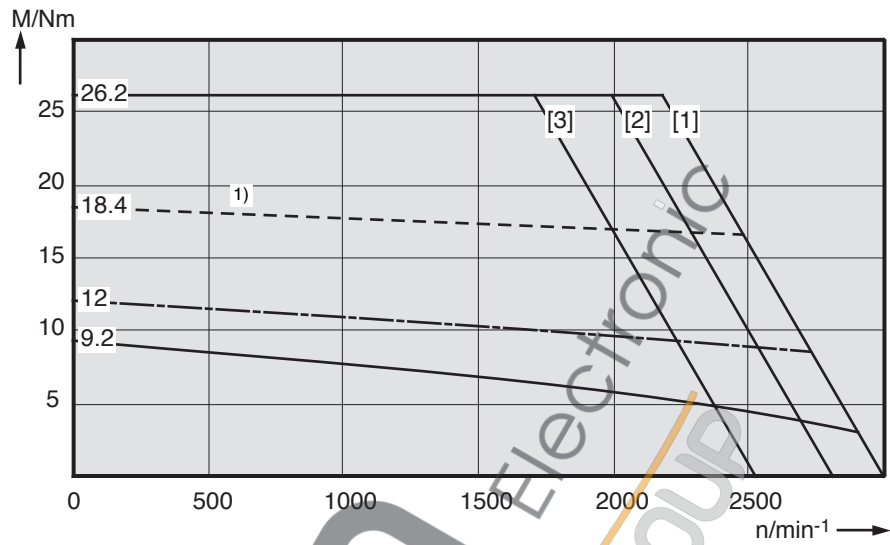
Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	S_N	VA	40/42	40/42
Nominal voltage	U_N	V	AC 230 or 115 ¹⁾	AC 230 or 115 ¹⁾
Frequency	f	Hz	50/60	50/60
Mass	m_L	kg	approx. 3.3 ²⁾	approx. 3.2 ²⁾
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

¹⁾ 115 V special design
²⁾ Blower shroud for motor with tachofeedback.

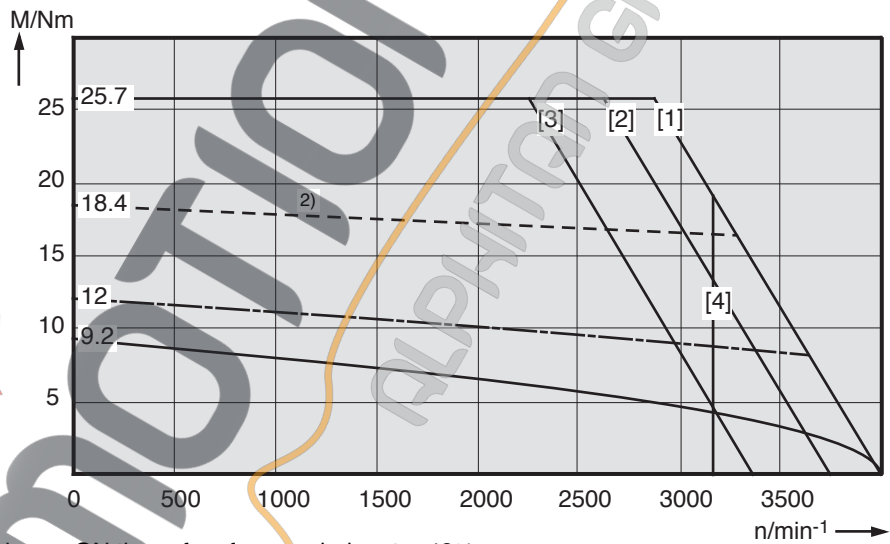
Fig 6.4: Technical data - surface cooling

6.2. Torque-Speed Characteristics

MAC 093 A - - - WS
2000 min⁻¹



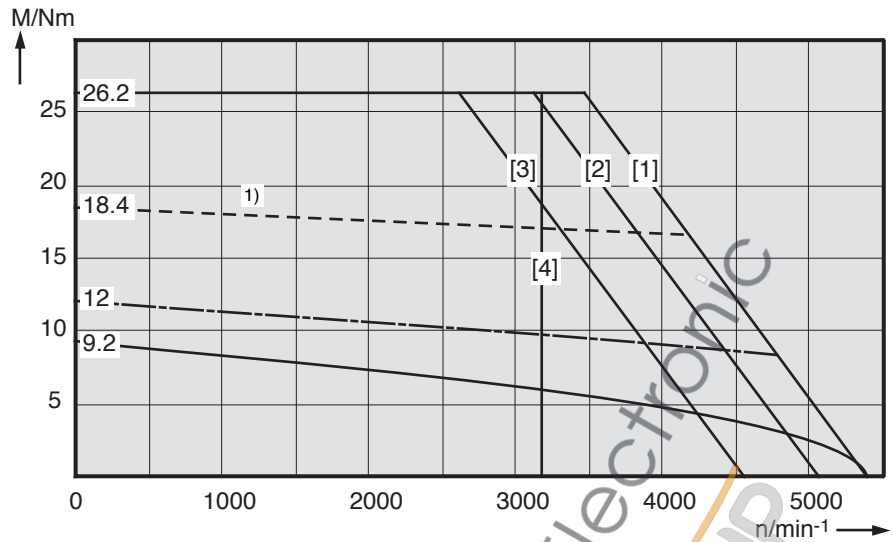
MAC 093 A - - - PS
3000 min⁻¹



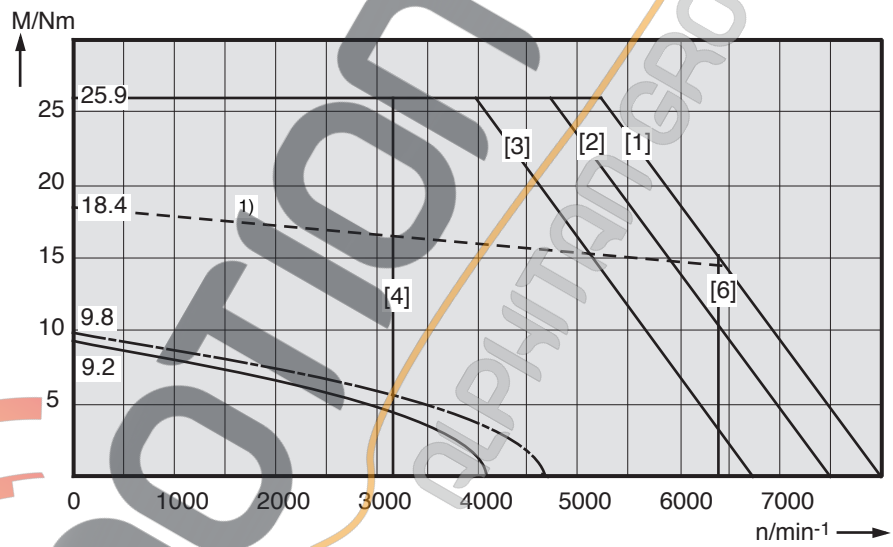
1) shown: ON time of surface-cooled motor 48%
2) shown: ON time of surface-cooled motor 40%

Fig 6.5: Torque-speed characteristics MAC 093

MAC 093 A - - - LS
4000 min⁻¹



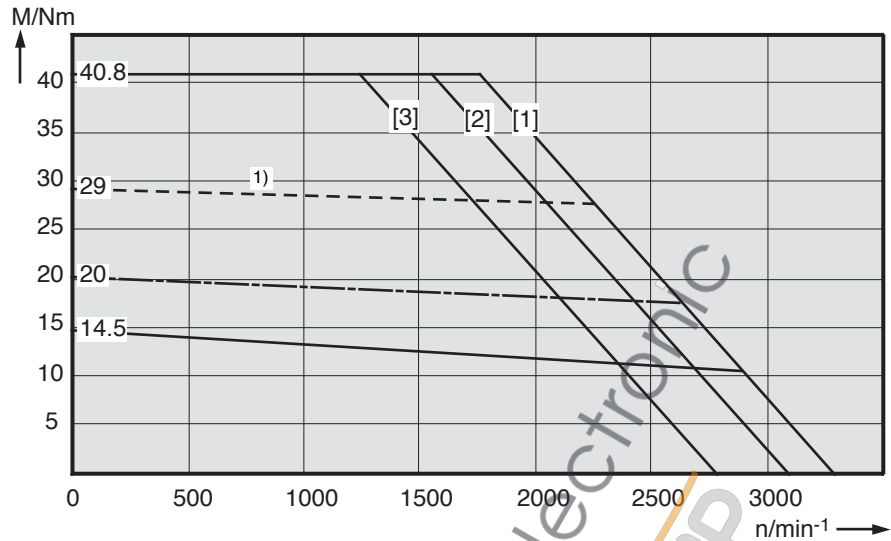
MAC 093 A - - - HS
6000 min⁻¹



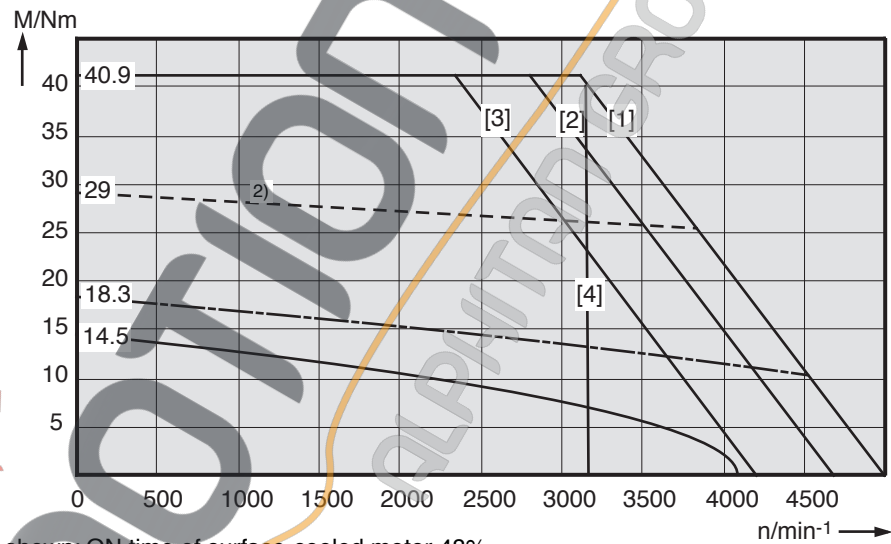
1) shown: ON time of surface-cooled motor 48%

Fig 6.6: Torque-speed characteristics MAC 093

MAC 093 B - - OS
2000 min⁻¹



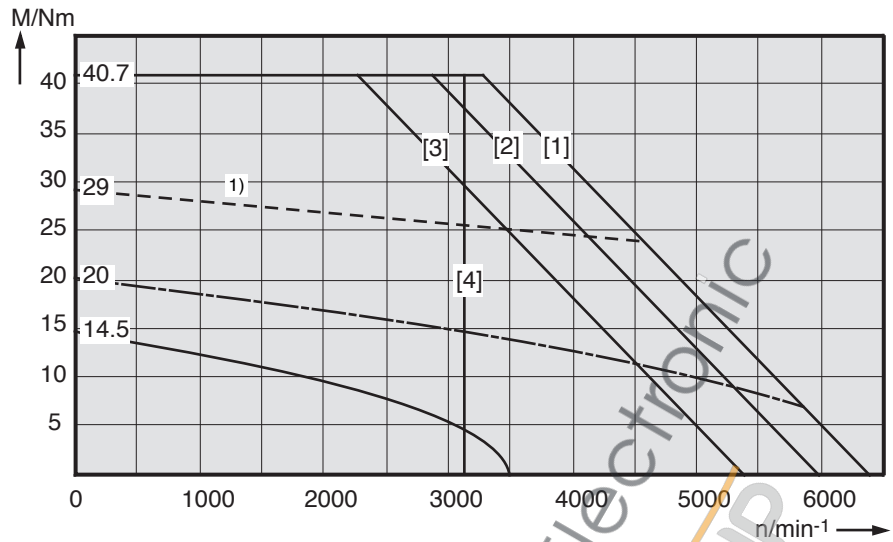
MAC 093 B - - JS
3000 min⁻¹



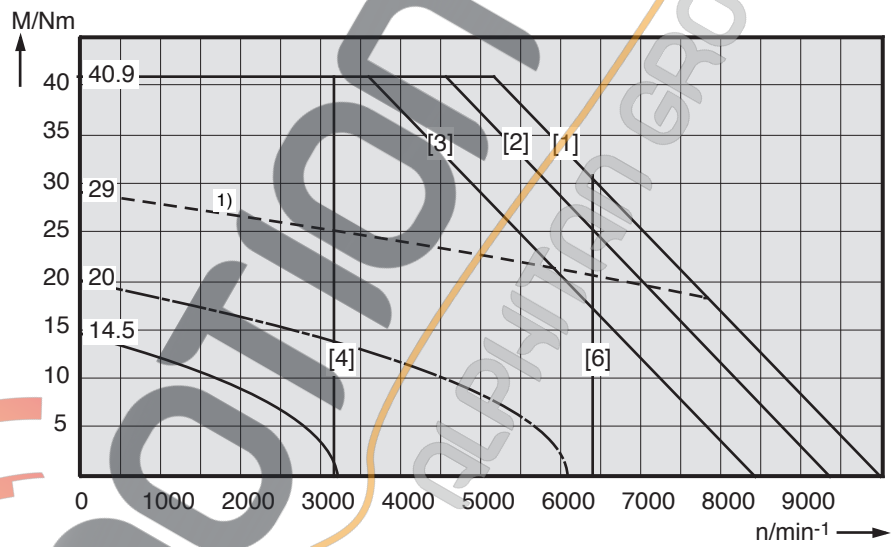
1) shown: ON time of surface-cooled motor 48%
1) shown: ON time of surface-cooled motor 40%

Fig 6.7: Torque-speed characteristics MAC 093

MAC 093 B - - - GS
4000 min⁻¹



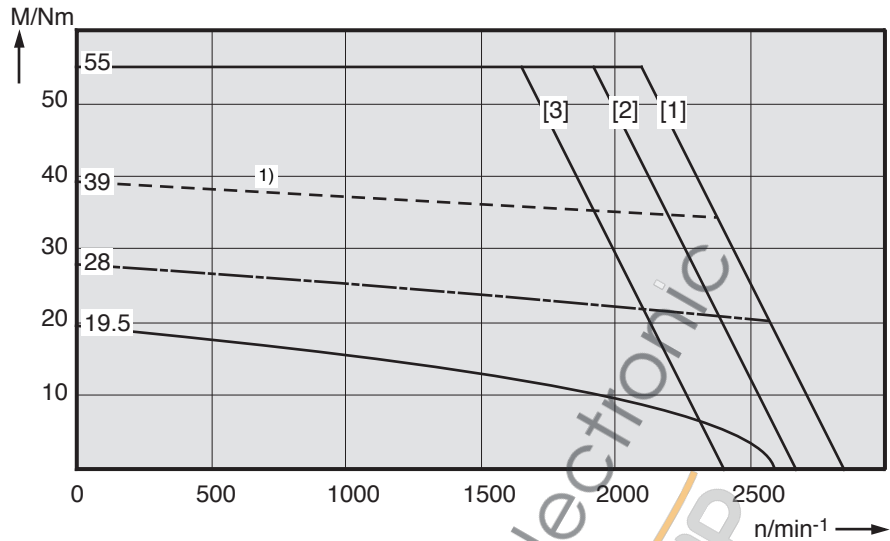
MAC 093 B - - - ES
6000 min⁻¹



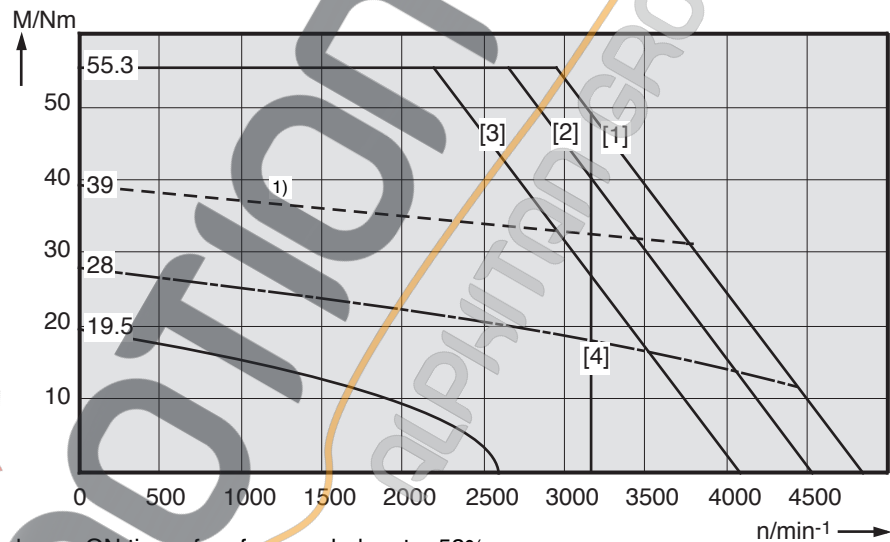
1) shown: ON time of surface-cooled motor 48%

Fig 6.8: Torque-speed characteristics MAC 093

MAC 093 C - - - KS
2000 min⁻¹



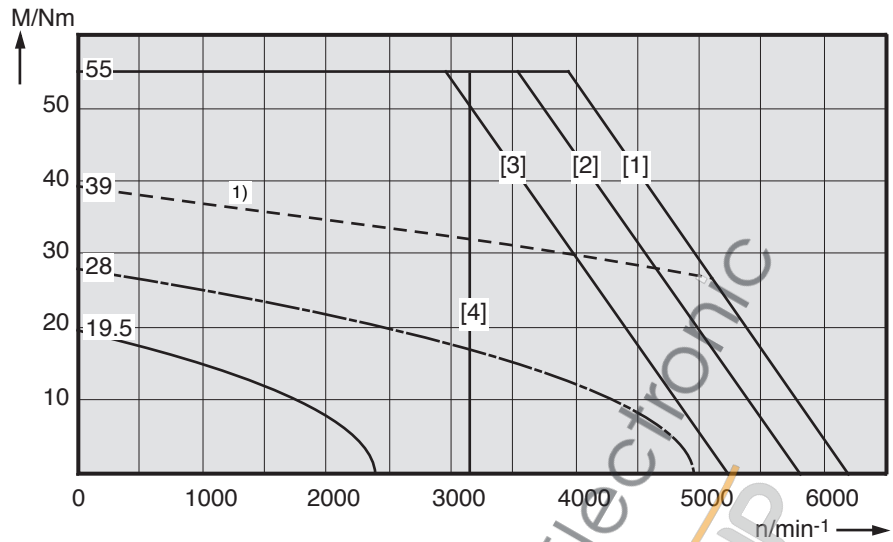
MAC 093 C - - - FS
3000 min⁻¹



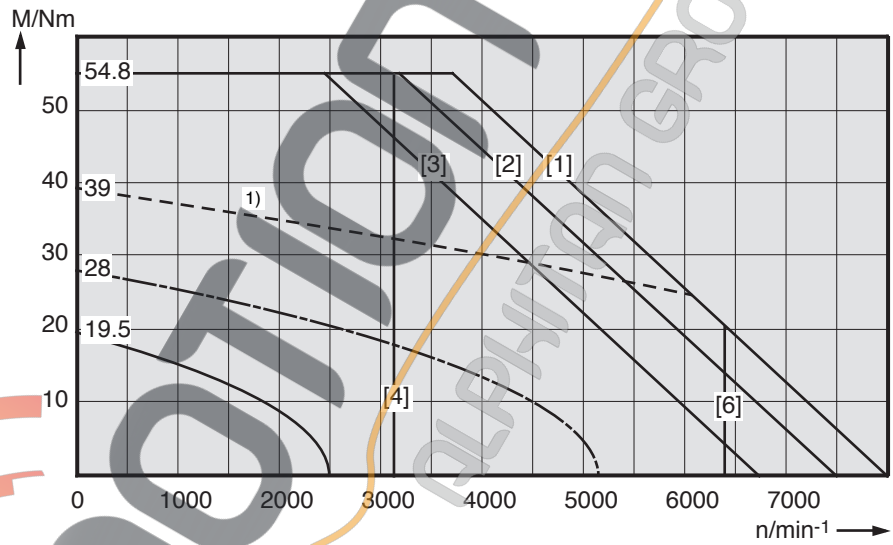
¹⁾ shown: ON time of surface-cooled motor 52%

Fig 6.9: Torque-speed characteristics MAC 093

MAC 093 C - - - DS
4000 min⁻¹



MAC 093 C - - - CS
6000 min⁻¹



1) shown: ON time of surface-cooled motor 52%

Fig 6.10: Torque-speed characteristics MAC 093

6.3. Shaft load capacity

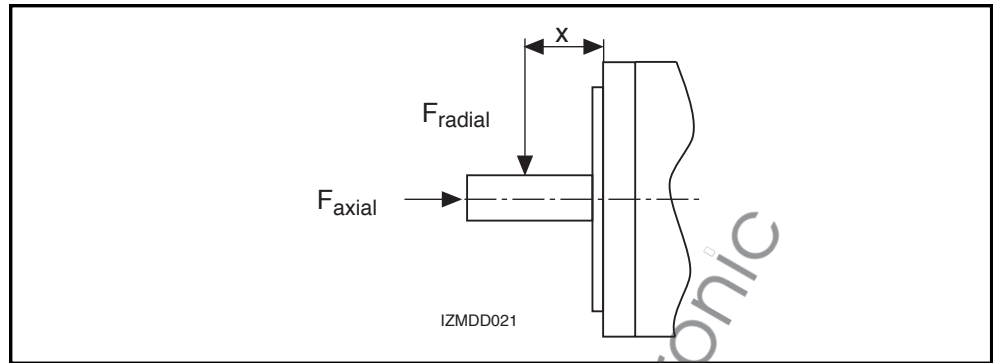


Fig 6.11: Shaft load

Permissible radial force
 F_{radial}

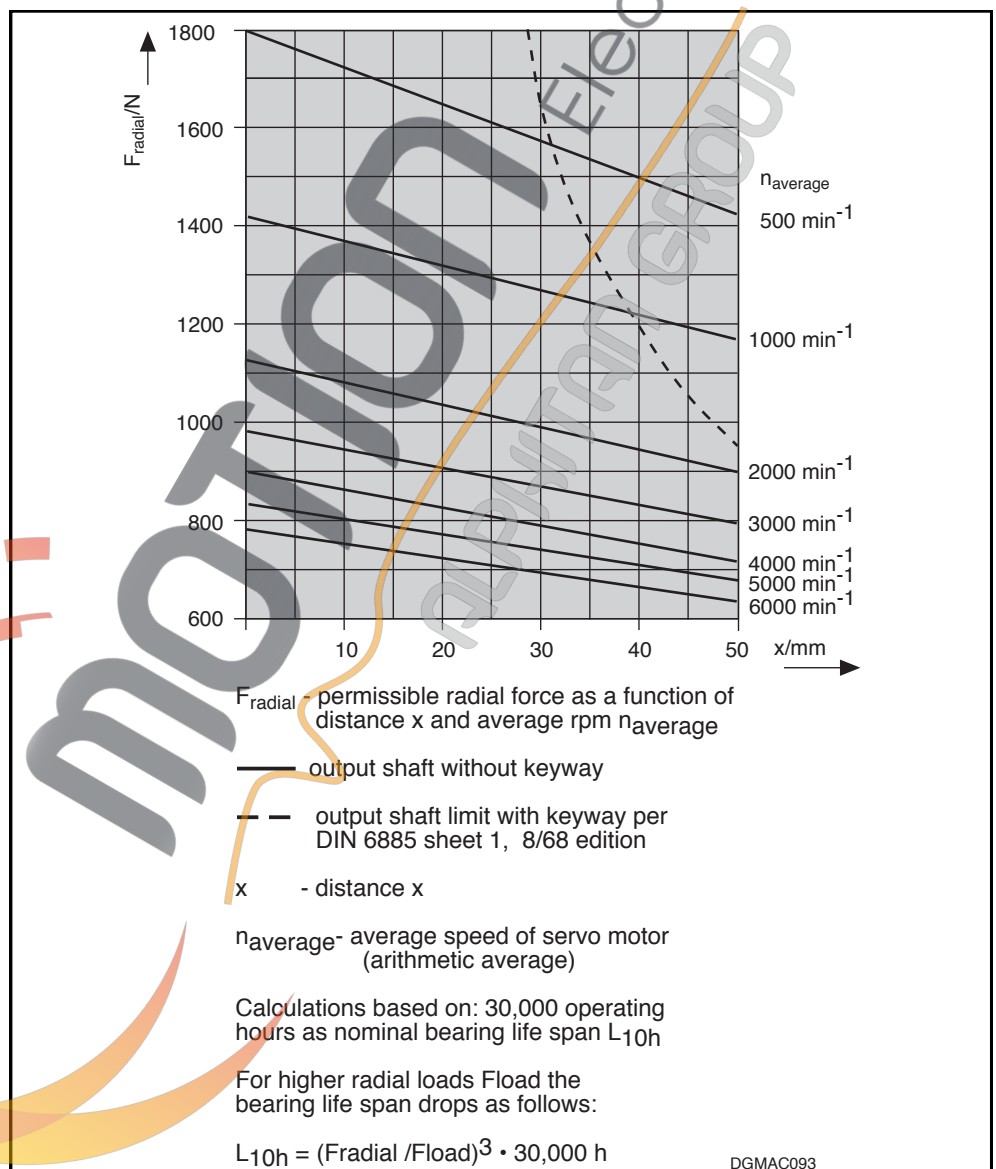


Fig 6.12: Permissible radial force

Permissible axial force
 F_{axial}

$$F_{axial} = 0.34 \cdot F_{radial}$$

F_{axial} - Permissible axial force
 F_{radial} - Permissible radial force

6.4. Dimensional data - natural convection

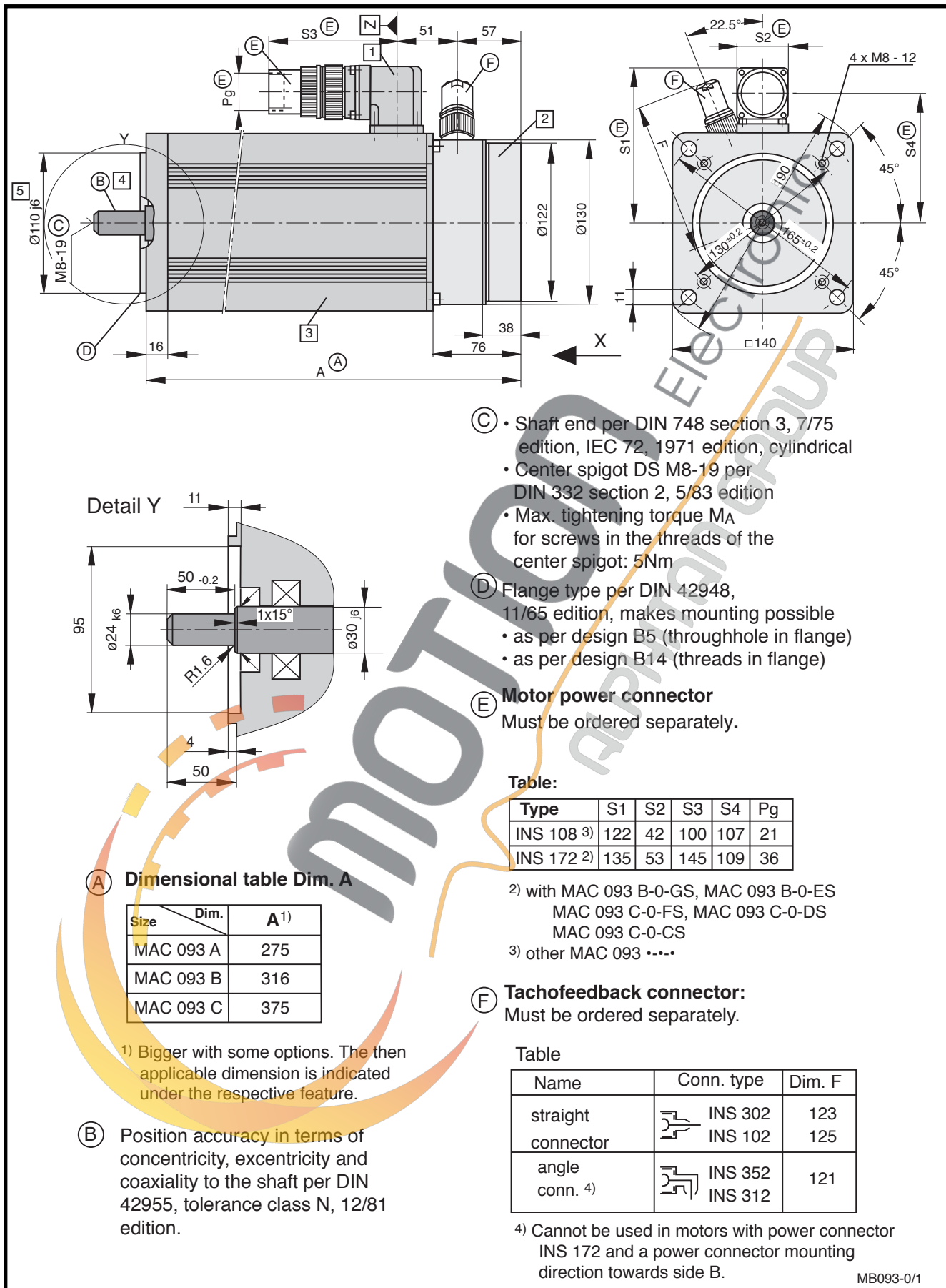


Fig 6.13: Dimensional data - MAC 093 (natural convection)

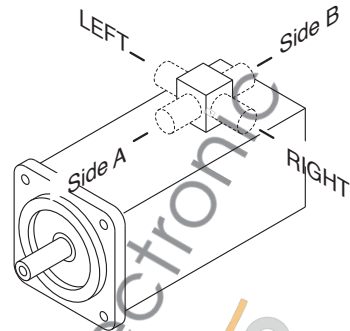
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

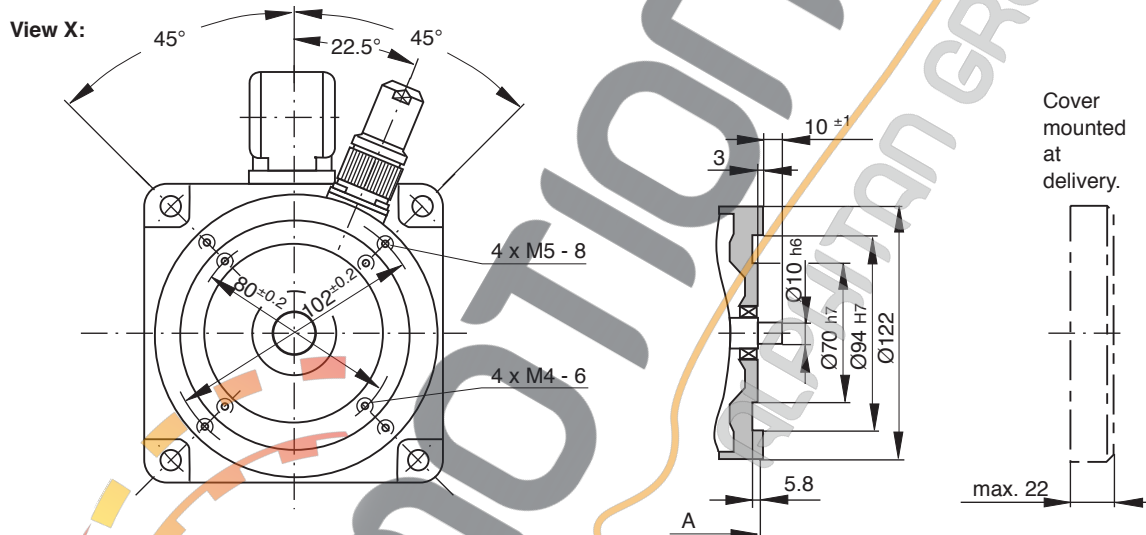
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

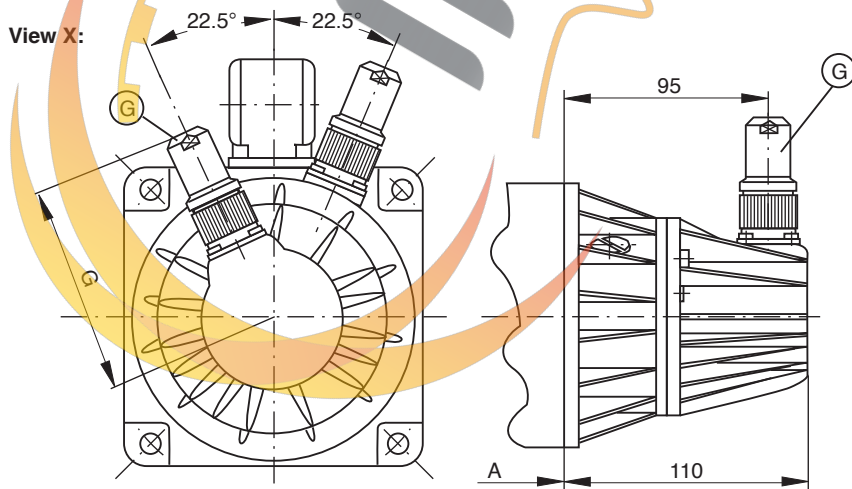


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	88
	INS 101	90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

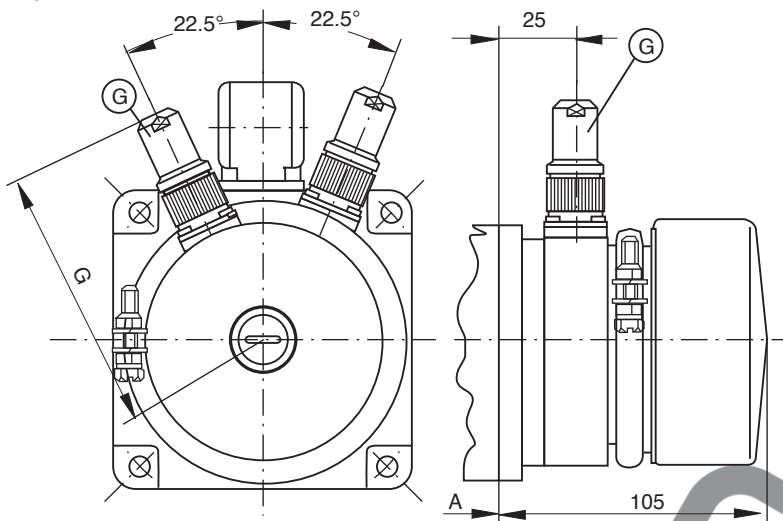
MB093-0/2

Fig 6.14: Dimensional data - MAC 093 - available options - (natural convection)

Available options

- Tachofeedback and mounted absolute encoder

View X:



Ⓒ Absolute encoder conn.
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106
angle conn.	INS 322	102

3 Blocking brake

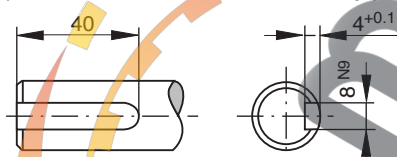
- without blocking brake
Dim. A retained
- Standard blocking brake: 6.5 Nm
Dim. A. retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 22 Nm

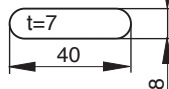
Size	Dim.	A
MAC 093 A		305
MAC 093 B		346
MAC 093 C		405

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 40
Must be ordered separately



5 Special centering diameter

- Ø130 j6

MB093-0/3

Fig 6.15: Dimensional data - MAC 093 - available options - (natural convection)

6.5. Dimensional data - radial cooling

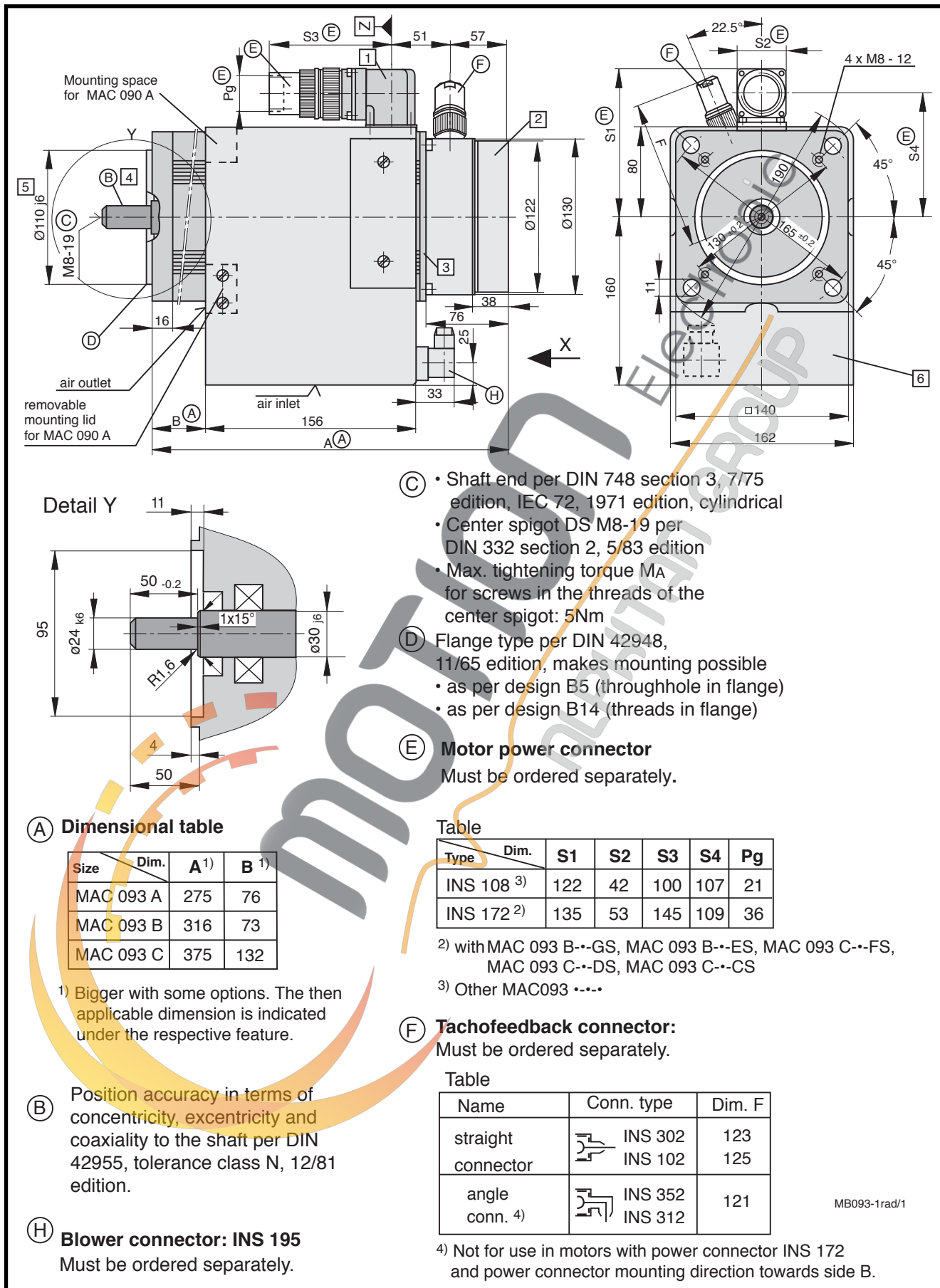


Fig 6.16: Dimensional data - MAC 093 (radial cooling)

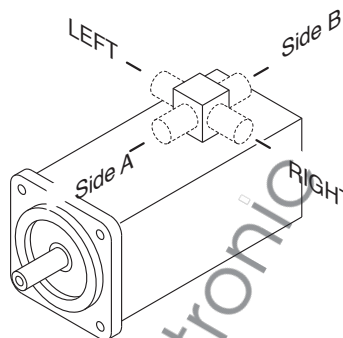
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B
- to the right
- to the left

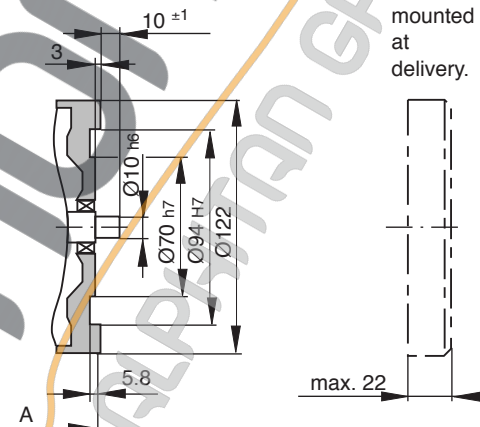
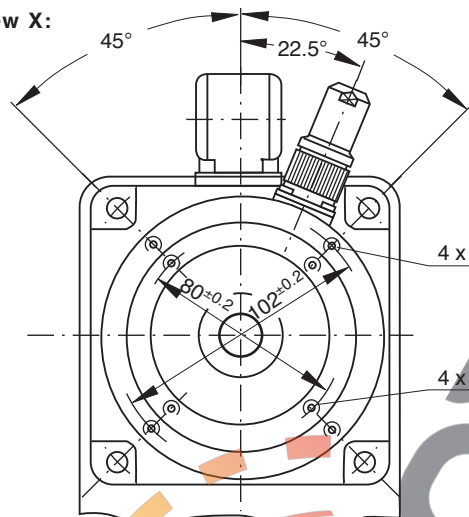
The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

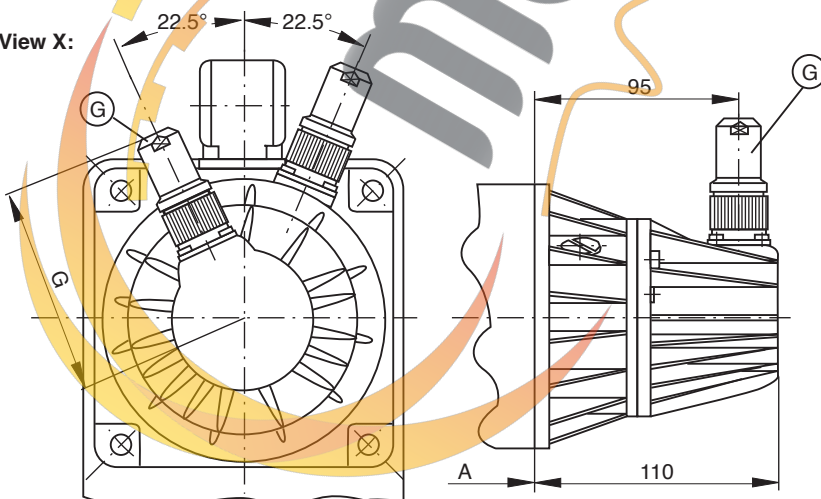
- Tachofeedback and second shaft end

View X:



- Tachofeedback and mounted incremental encoder

View X:



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	88
	INS 101	90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

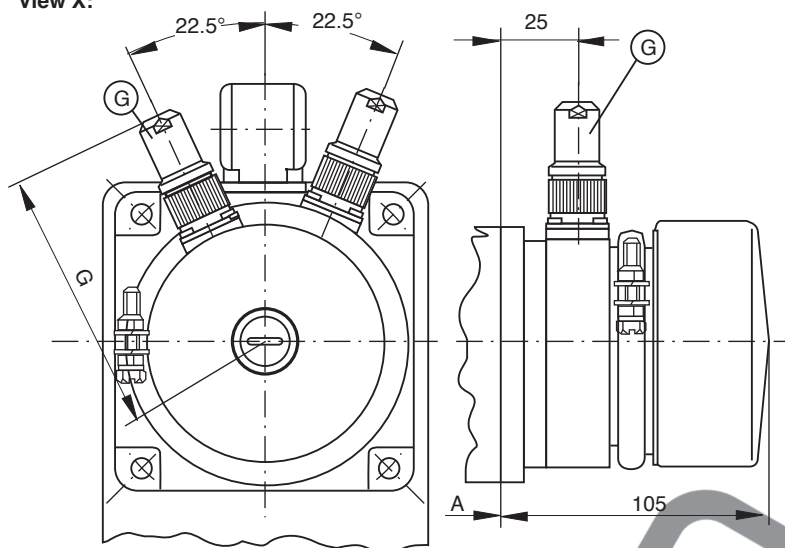
MB090-1rad/2

Fig 6.17: Dimensional data - MAC 093 - available options - (radial cooling)

Available options

- Tachofeedback and mounted absolute encoder

View X:



Ⓒ **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106
angle conn.	INS 322	102

3 Blocking brake

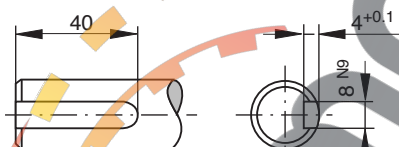
- without blocking brake
Dim. A and B retained
- Standard blocking brake: 6.5 Nm
Dim. A and B retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 22 Nm

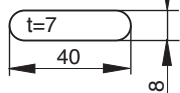
Size	Dim.	A	B
MAC 093 A		305	106
MAC 093 B		346	103
MAC 093 C		405	162

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 40
Must be ordered separately.

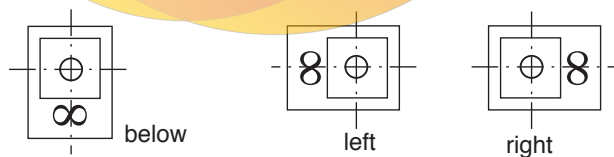


5 Special centering diameter

- $\varnothing 130 j6$

6 Blower arrangement

Looking towards motor shaft.



MB093-1rad/3

Fig 6.18: Dimensional data - MAC 093 - available options - (radial cooling)

6.6. Dimensional Data - Axial Cooling

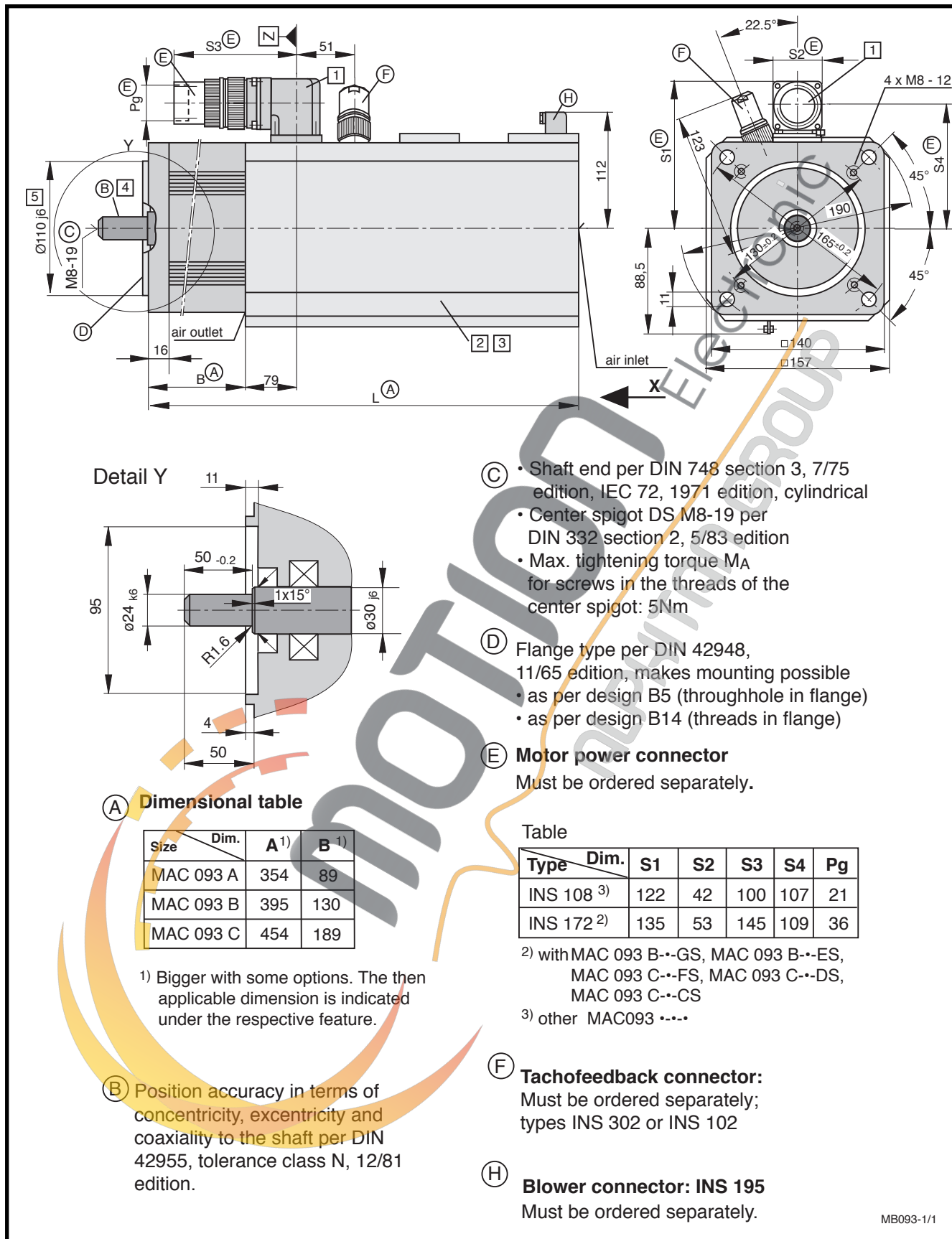


Fig 6.19: Dimensional data - MAC 093 (axial cooling)

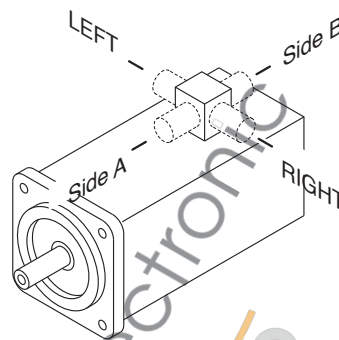
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

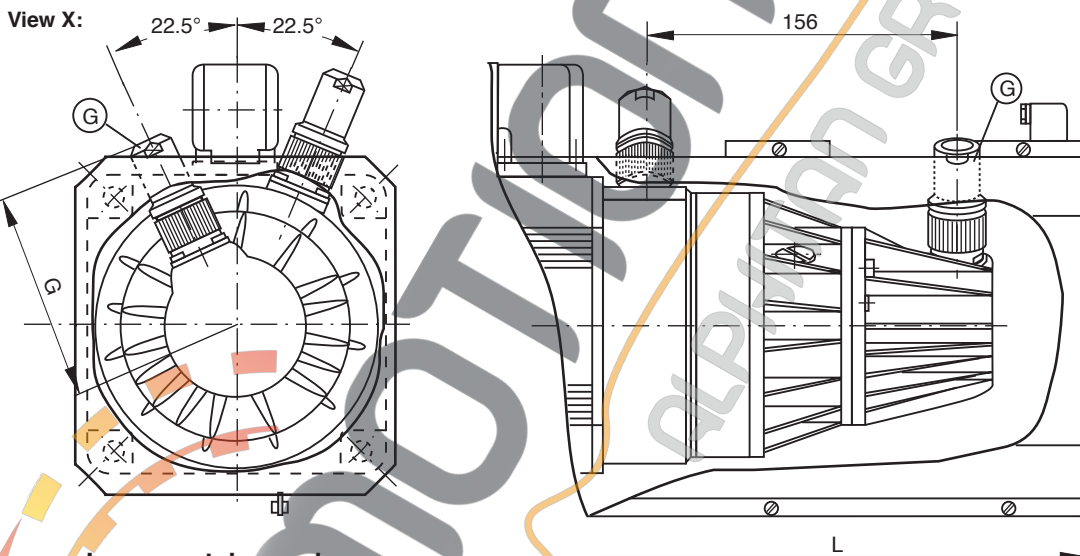
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

- Tachofeedback and mounted incremental encoder



G Incremental encoder connector
Must be ordered separately.

Name	Conn. type	Dim. G
straight	INS 301	123
conn.	INS 101	125

Table:

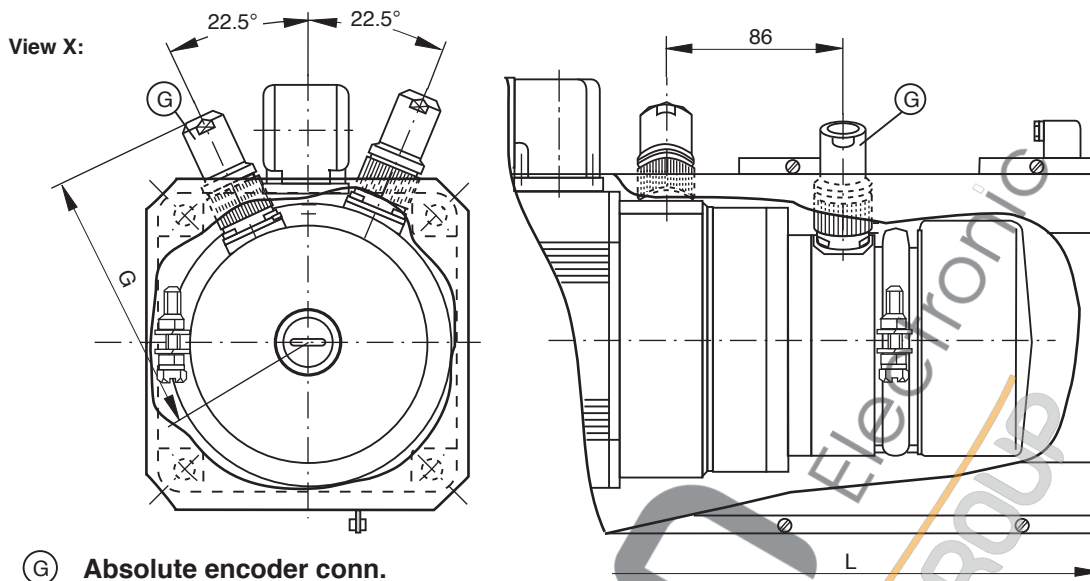
Size	Dim.	L	B
MAC 093 A		454	89
MAC 093 B		495	130
MAC 093 C		554	189

MB093-1/2

Fig 6.20: Dimensional data - MAC 093 - available options - (axial cooling)

Available options

- Tachofeedback and mounted absolute encoder



G Absolute encoder conn.
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106

Size	Dim.	L	B
MAC 093 A		454	89
MAC 093 B		495	130
MAC 093 C		554	189

3 Blocking brake

- without blocking brake
Dim. L and B retained
- Standard blocking brake: 6.5 Nm
Dim. L and B retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

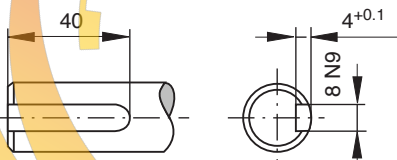
Table for blocking brake with 14 and 20 Nm

Size	Dim.		Vers. 4	
	L	B	L	B
MAC 093 A	384	119	484	119
MAC 093 B	425	160	525	160
MAC 093 C	484	219	584	219

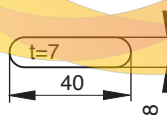
Vers. 2 = Motor with tachofeedback
Vers. 4 = Motor with tachofeedback and mounted encoder

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 50
Must be ordered separately.



5 Special centering diameter

- Ø130 j6

MB093-1/3

Fig 6.21: Dimensional data - MAC 093 - available options - (axial cooling)

6.7. Available Options

Example: **MAC 093 A-0-LS-4 - C/110-A-0/WI 520LV/S000**

Type code fields		Example: MAC	
1. Motor for analogue drives	MAC		
2. Motor size	093		
3. Motor length	A, B, C		
4. Type of cooling:			
natural convection		surface cooling	
0	axial		radial
			blower right blower below blower left
	AC 230 V 1 ¹⁾	AC 115 V 2 ¹⁾	AC 230 V AC 115 V AC 230 V AC 115 V 6 A 7 B 8 C
5. Type of windings			
Nominal rpm	Motor length		
	A	B	C
2000 min ⁻¹	WS	OS	KS
3000 min ⁻¹	PS	JS	FS
4000 min ⁻¹	LS	GS	DS
6000 min ⁻¹	HS	ES	CS
6. Motor feedback			
Motor type			
with tachofeedback	2		
with tachofeedback and second shaft end	3		
with tachofeedback and mounted incremental or absolute encoder	4		
Tacho voltage			
set to nominal motor speed	-		
(nominal rpm > 3000 min ⁻¹) : 1.5 V/1000 min ⁻¹)			
(nominal rpm ≤ 3000 min ⁻¹) : 3 V/1000 min ⁻¹)			
1.5 V/1000 min ⁻¹	H		
Tacho type			
Standard	C		
increased smooth run quality	F		
7. Centering diameter			
for design B05 and B14	110		
for design B05 and B14	130		
8. Power connection			
connector to side A	A		
connector to side B	B		
connector to right (looking onto output shaft)	R		
connector to left (looking onto output shaft)	L		
9. Blocking brake			
without blocking brake	0		
with standard blocking brake (6.5 Nm)	1		
with heavy-duty blocking brake (14 Nm)	2		
with extra heavy-duty blocking brake (22 Nm)	3		
10. Type ²⁾			
Mounted encoder	Incremental encoder with standard mounting	WI	
	Incremental encoder with shock-damped mounting	DI	
	Absolute encoder	AM	
11. Encoder code ²⁾			
For available types, see section 2.4 "Motor feedback"			
12. Special types			
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)			
Does not apply to standard motors.			

1) For type 3 motors (with 2nd shaft end and tachofeedback).
Not available with axial surface cooling.

2) Type code fields 10 and 11 do not apply to motor types 2 and 3.

TLMAC093

Fig 6.22: Type codes - MAC 093

6.8. Special Options

Specification of Option	S005
with keyway per DIN 6885, sheet 1	X

Fig 6.23: Special options with a MAC 093

